

Exact extreme value statistics at mixed order transitions

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We study extreme value statistics (EVS) for spatially extended models exhibiting mixed order phase transitions (MOT). These are phase transitions which exhibit features common to both first order (discontinuity of the order parameter) and second order (diverging correlation length) transitions. We consider here the truncated inverse distance squared Ising (TIDSI) model which is a prototypical model exhibiting MOT, and study analytically the extreme value statistics of the domain lengths. The lengths of the domains are identically distributed random variables except for the global constraint that their sum equals the total system size L . In addition, the number of such domains is also a fluctuating variable, and not fixed. In the paramagnetic phase, we show that the distribution of the largest domain length l_{\max} converges, in the large L limit, to a Gumbel distribution. However, at the critical point (for a certain range of parameters) and in the ferromagnetic phase, we show that the fluctuations of l_{\max} are governed by novel distributions which we compute exactly. Our main analytical results are verified by numerical simulations.

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I. INTRODUCTION

Extreme events are generally rare, but their implications may be of major importance. Hence, the theory of such events has found many applications in diverse fields such as geology (*e.g.*, earth-quakes analysis), economy (*e.g.*, stock market fluctuations), physics (*e.g.*, properties of ground states of disordered systems) or biology (*e.g.*, evolution theory). The theory of extreme value statistics (EVS) for independent and identically distributed (i.i.d.) random variables is well known since the work of Tippet, Fisher, Fréchet, Gumbel, Weibull and others [1–5]. However, the study of extreme values for sets of correlated variables is an active field of research (for a recent review see [6]). In this work we study a specific class of correlated variables, which represent degrees of freedom of a spatially extended system poised in a rather unconventional type of critical point, named mixed order phase transition (MOT).

MOTs are phase transitions in which the order parameter changes discontinuously, as in first order transitions, but exhibit diverging correlation length and scale free distributions as in continuous transitions. Such transitions appear in several distinct contexts including one-dimensional Ising model with long range interactions [7–9], models of DNA denaturation [10, 11], wetting and depinning transitions [12, 13], models for glass and jamming transitions [14–17], complex network evolution [18–21] or active biopolymer gels [22, 23]. While it is clear that these transitions do not fall into the ordinary classification scheme of phase transitions, there is currently no theoretical framework

which provides a comprehensive classification of such transitions. One clear distinction between different MOTs is the behavior of the correlation length near the transition: in some cases its divergence is polynomial in the control parameter (*e.g.* in the Poland-Scheraga model [10] and in the No-Enclave Percolation model [23]), while in others the correlation length exhibits an essential singularity, in the form of stretched exponential divergence (*e.g.* in the Inverse Distance Squared Ising model [7] or in the Spiral model for jamming [15]). Recently [24, 25], this distinction in the behavior of the correlation length was studied in a one-dimensional setting, using renormalization group (RG) analysis to study, on the same footing, models from both classes. It is an ongoing research task to find other relations and distinctions between such transitions, or at least a framework in which they can be analyzed together. Here we highlight EVS as unifying concepts for such transitions.

In the examples for MOT mentioned above, mixed order transitions separate a phase composed of microscopic domains from a phase in which a macroscopic domain exists. For instance, in the context of DNA denaturation, the relevant domains are denatured regions, and the MOT involves the appearance of a macroscopic denatured region. In the context of network evolution, the relevant domains are the connected components, and a macroscopic domain is a spanning cluster. The transition itself can be identified with the change in the scaling of the maximal domain size with the total system size: the largest domain is sub-extensive below the transition, and extensive above it. Hence, it is natural in this context to study the extreme value statistics (EVS) of the set of domain sizes.

Obtaining exact results for EVS of generally correlated variables, such as domain sizes in a network evolution model, is notoriously hard. In order to gain analytical insight into this problem we study it in the context of the truncated inverse distance squared Ising model (TIDSI), which was introduced in [24] as a bridge between models exhibiting MOT in one dimension. The sizes of domains in a configuration of the TIDSI model are essentially independent variables, apart for a sum constraint which generates correlations [see Eq. (7) below]. In addition, the number of domains is fluctuating. Due to this special structure, many properties of this model, including the extreme value theory of its domain sizes, are analytically accessible. We find that the EVS distribution can be either standard independent-variables distribution or novel EVS distributions, depending on control parameters of the model.

In this paper we derive the EVS of the TIDSI model analytically and discuss its important features. The paper is organized as follows. In section II we introduce the TIDSI model, discuss its various representations and recall its phase diagram. In section III we discuss the extreme value theory of the TIDSI, which is the main result of this paper. In section IV we discuss the direct relation between the TIDSI and other one-dimensional models which exhibit MOT. Finally we discuss our findings in section V. For completeness, we review basic results for EVS of i.i.d. random variables in Appendix A. Some technical details have been relegated in Appendix B and C.

II. THE MODEL

The TIDSI model was introduced in [24] and further analyzed in [25]. Originally, the TIDSI was defined as an Ising spin chain with specific long range interactions. However, in this paper we will focus on its representation in terms of spin domains (see Fig. 1), in the regime in which the relevant domains are large and hence terms inversely proportional to domain length can be neglected. We start by reminding the readers the original TIDSI model in the spin representation and then derive its domain representation.

Spin representation. In its spin chain representation the TIDSI model is defined on a spin chain of size L . At each site there is an Ising spin $\sigma_i = \pm 1$. There is a standard nearest neighbor ferromagnetic interaction between spins. In addition, there is a ferromagnetic long range interaction between spins belonging to the same domain, where a domain is a consecutive set of spins of the same sign (see Fig. 1). Thus the long range interaction is truncated by the finite domain size. We consider the case where the long range interaction decays asymptotically

according to an inverse quadratic law. The full Hamiltonian of the system in the spin representation thus reads

$$\mathcal{H} = -J_{NN} \sum_{i=1}^{N-1} \sigma_i \sigma_{i+1} - \sum_{i < j} J(i-j) \sigma_i \sigma_j \prod_{k=i}^{j-1} \frac{1 + \sigma_k \sigma_{k+1}}{2}, \quad (1)$$

$$J(r) \approx Cr^{-2}, \quad r \gg 1. \quad (2)$$

The product in the second term of Eq. (1) ensures that the long range interaction is restricted to spins within the same domain. We consider here free boundary conditions.

Domain representation. A typical configuration of the system will consist of alternating spin domains characterized by sizes $\{l_1, l_2, \dots, l_N\}$ (see Fig. 1) where N is the number of domains, which may also vary from configuration to configuration. Note that the variables l_i 's satisfy the constraint

$$\sum_{i=1}^N l_i = L \quad (3)$$

where L is the system size. In terms of these domains, the Hamiltonian can be re-expressed as

$$\mathcal{H} = \sum_{n=1}^N \mathcal{H}_n - J_{NN}, \quad (4)$$

$$\mathcal{H}_n = -J_{NN} (l_n - 2) - \sum_{r=1}^{l_n} (l_n - r) J(r). \quad (5)$$

For any long range interaction $J(r)$ that satisfies $r^2 J(r) \rightarrow C$ as $r \rightarrow \infty$, we have

$$\begin{aligned} \sum_{r=1}^{l_n} J(r) &= a - \frac{C}{l_n} + \mathcal{O}(l_n^{-2}) \\ \sum_{r=1}^{l_n} r J(r) &= b + C \log l_n + \mathcal{O}(l_n^{-1}). \end{aligned}$$

For large enough domains we can ignore $\mathcal{O}(l_n^{-1})$ corrections. As we will see later, this is justified near the critical point where the domains are typically very large. Using the sum rule $\sum_{i=1}^N l_i = L$, the linear term $-(J_{NN} + a) l_n$, summed over n , just becomes a constant and hence can be dropped. Hence, under the approximation of long domains the Hamiltonian is re-expressed as

$$\mathcal{H} = C \sum_n \log l_n + \Delta N. \quad (6)$$

Here C is a constant parameter and $\Delta = 2J_{NN} + C + b$ serves as a chemical potential for the number of domains.

In this domain representation, a configuration \mathcal{C} of the system is specified by the domain sizes $\{l_1, l_2, \dots, l_N\}$ and the number N of domains (see Fig. 1). The Boltzmann weight associated with such a configuration \mathcal{C} is simply $P(\mathcal{C}) \propto e^{-\beta \mathcal{H}}$, where $\beta = 1/(k_B T)$ is the inverse temperature and the Hamiltonian \mathcal{H} is given in Eq. (6). This then leads to the following joint distribution of the domain lengths and their number

$$P(l_1, l_2, \dots, l_N, N | L) = \frac{1}{Z(L)} \prod_{n=1}^N \frac{e^{-\beta \Delta}}{l_n^c} \delta_{\sum_{n=1}^N l_n, L}, \quad (7)$$

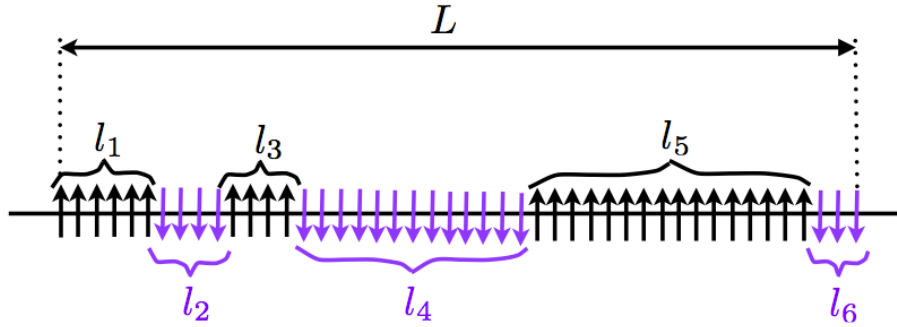


FIG. 1. Domain representation of the TIDSI model of size L . In this configuration, the number of domains is $N = 6$. We recall that the interaction is restricted to spins within the same domain. The Boltzmann-Gibbs weight of such a configuration is given by Eq. (7). In this paper we study the statistics of the largest domain length $l_{\max} = \max_{1 \leq i \leq N} l_i$.

where $\delta_{i,j}$ is the usual Kronecker delta and $c = \beta C$. For the purpose of the normalization of the full joint distribution, we need here $c > 1$. The normalization constant $Z(L)$ is the partition function given by

$$Z(L) = \sum_{N=1}^{\infty} \sum_{l_1=1}^{\infty} \cdots \sum_{l_N=1}^{\infty} \prod_{n=1}^N \frac{e^{-\beta \Delta}}{l_n^c} \delta_{\sum_{n=1}^N l_n, L}. \quad (8)$$

The two natural parameters in the model are the inverse temperature β and the fugacity $e^{-\beta \Delta}$. For convenience, we will use an alternative parameterization in terms of the exponent c characterizing the power law decay of the domain size distribution and the temperature T . We note that this model has close similarity to the Poland-Scheraga model of DNA denaturation where the number of loops N is also a variable (see later in section IV for discussions).

Phase diagram. The phase diagram of the TIDSI model in the (c, T) plane was derived in [25] (see Fig. 2). For completeness we briefly summarize the main results (for zero magnetic field). There are two relevant order parameters for the TIDSI model: the density of domains $\rho = \frac{N}{L}$, and the magnetization $m = \sum_{n \geq 1} (-1)^n l_n$ [25]. For any C and $\Delta > 0$, a phase transition is predicted at some $T_c(C, \Delta)$ which is given by

$$\zeta(\beta_c C) = e^{\beta_c \Delta}. \quad (9)$$

Here $\beta_c = k_B T_c^{-1}$ and $\zeta(\gamma) = \sum_{n=1}^{\infty} n^{-\gamma}$ is the Riemann zeta function. In Fig. 2 the phase diagram is presented in the (c, T) plane. The critical line in Fig. 2 separates a high temperature paramagnetic phase, in which $m = 0$ and $\rho > 0$, and a low temperature ferromagnetic phase in which $m = \pm 1$ and $\rho = 0$. The ferromagnetic phase is a *condensed* phase, in which all but a sub-extensive part of the system is in a single macroscopic domain. The critical line has three different regimes: In regime I ($1 < c \leq 2$) the magnetization jumps from 0 to ± 1 abruptly, while the density of domains drops continuously to 0 in the paramagnetic phase as one approaches the critical line. In regimes II ($2 < c \leq 3$) and III ($c > 3$) both m and ρ change discontinuously. In regime II the magnetic susceptibility diverges at the transition, while in regime III it is finite (see [25] for definition of magnetic susceptibility in this context). In all regimes the spin-spin correlation length diverges, and hence the transition is critical.

In this paper, the main focus is not on the thermodynamics of this model but rather on the statistics of the largest domain l_{\max} . As discussed above, this is a natural observable since the transition from paramagnetism to ferromagnetism occurs via the emergence of a macroscopic domain as one crosses the critical line. We show in this paper that the statistics of the largest domain indeed has an extremely rich and novel behavior in different regions of the phase diagram in the (c, T) plane.

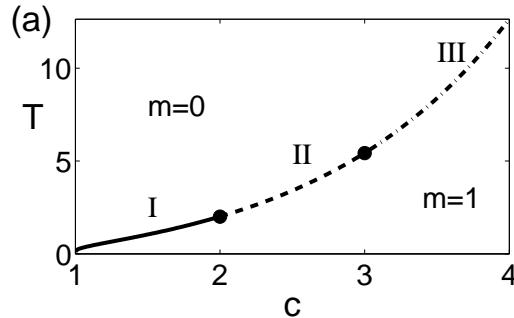


FIG. 2. Phase diagram of the model (6) in the (c, T) plane, with $\Delta = 1$. The different regions of the critical line (I-III) are explained in the text.

III. STATISTICS OF THE LARGEST DOMAIN

In the domain representation the system is characterized by a fluctuating number of domains N with domain lengths l_i 's distributed according to the joint probability density function (PDF) given in Eq. (7). We define the largest domain size as $l_{\max} = \max_{1 \leq n \leq N} l_n$. This is clearly a random variable and we are interested in computing its PDF, in particular in the thermodynamic limit $L \rightarrow \infty$, in the various regions of the phase diagram in the (c, T) plane. Note that due to (i) the presence of the global constraint $\sum_{n=1}^N l_n = L$ in Eq. (7) and (ii) the fluctuating number of domains N , the variables l_n 's are correlated and therefore the standard extreme value statistics (EVS) of uncorrelated variables are not valid here. Indeed we will see that these two facts lead to results for l_{\max} that are rather different from and richer than the standard EVS results.

At this point, it is useful to point out that l_{\max} has been recently studied in models that are similar but not exactly identical to the present case. For example, in the case of zero range process (ZRP), the joint distribution of the number of particles at different sites of a lattice of size N has a similar structure as in Eq. (7):

$$P_{\text{ZRP}}(l_1, \dots, l_N | L) \propto \prod_{n=1}^N \frac{1}{l_n^c} \delta_{\sum_{n=1}^N l_n, L}, \quad (10)$$

where l_n represents the number of particles at site n and L represents the total number of particles. The statistics of l_{\max} in this case (10) has been studied in Ref. [26]. Even though structurally Eq. (10) is similar to the joint PDF in Eq. (7), there are two important differences: (i) the number of sites N is fixed and hence (ii) there is no explicit fugacity.

Similarly, the largest time interval between returns to the origin has been studied for one-dimensional lattice random walks [27] and more generally for renewal processes [28, 29]. In this case, the joint PDF of the intervals between renewals is given by

$$P_{\text{REN}}(l_1, \dots, l_N, N | L) \propto \left[\prod_{n=1}^{N-1} f(l_n) \right] q(l_N) \delta_{\sum_{n=1}^N l_n, L}, \quad (11)$$

where l_n 's represent the intervals between renewal events and L represents the total time interval. Here the number of intervals N is a variable as in Eq. (7). However, unlike in Eq. (7), the first $N-1$ intervals have the same weight $f(l_n)$ but the last one has a different weight $q(l_N) = \sum_{l=l_N+1}^{\infty} f(l)$. In addition, there is no explicit fugacity as in Eq. (7). In these renewal processes (11), the weight $f(l)$ is taken as an input in the model. In contrast, in the TIDSI

model the renewal structure along with the weight $f(l) \propto l^{-c}$ emerge naturally from the Boltzmann weight of an underlying Hamiltonian. Hence the joint PDF in Eq. (7) has a richer structure as it can be studied in the various regions of the parameter space in the (c, T) plane. Consequently, we will see that the results for the statistics of l_{\max} in the TIDSI model also have a richer structure as summarized below.

A. Summary of main results

Our main results concern the exact expression for the cumulative distribution of the largest domain, $P_1(x) = \text{Pr.}(l_{\max} \leq x)$, or equivalently for its distribution $p_1(x|L) = \text{Pr.}(l_{\max} = x)$, in the large L limit, in the various regions of the phase diagram in the (c, T) plane (see Fig. 2 and Table I).

- $T > T_c$: in the paramagnetic phase, the marginal distribution of the domain size has an exponential tail $P(l) \sim l^{-c} e^{-l/\xi}$ where $\xi \equiv \xi(T, c)$ is the typical domain size, which is finite for $T < T_c$ [24, 25]. In this case, we show that the maximal domain size l_{\max} , properly shifted and scaled, is distributed according to a Gumbel distribution (see also Fig. 3 below):

$$P_1(x|L) \approx \exp \left[-\exp \left(-\left(\frac{x - b_L}{a} \right) \right) \right], \quad (12)$$

where b_L , which depends explicitly on L , and a , which is independent of L , are given by

$$a = -\frac{1}{\log(z^*)}, \quad b_L = a \log \left[\frac{z^* L}{(1 - z^*) \text{Li}_{c-1}(z^*) (a \log L)^c} \right], \quad (13)$$

where $\text{Li}_c(z) = \sum_{l \geq 1} \frac{z^l}{l^c}$ is the polylogarithm function and z^* is determined by the relation

$$\text{Li}_c(z^*) = e^{\beta \Delta}. \quad (14)$$

This result (12) implies that in the paramagnetic phase, the average value of the largest domain scales logarithmically with L , $\langle l_{\max} \rangle \approx b_L \approx a \log L$. In this phase, the PDF of the l_n 's has an exponential tail and besides, the typical number of domains is $\propto L$. Therefore, the fact that the limiting distribution is given by a Gumbel law (12), which is known to describe the EVS of i.i.d. variables with an exponential tail [4] (see also Appendix A), shows that the correlations among the l_n 's, generated by the global constraint in Eq. (7), do not play any role for $T > T_c$. Note that a similar property was found for renewal processes with exponentially distributed intervals in Ref. [29].

- $T = T_c$: along the critical line, the marginal distribution of the domain size has an algebraic tail $P(l) \sim l^{-c}$. In this case, we find that depending on the value of c ($c > 2$ or $1 < c < 2$), the PDF of l_{\max} exhibits two different behaviors.

- (i) If $c > 2$, we show that the limiting distribution is asymptotically given by a Fréchet distribution (see also Fig. 6 below):

$$P_1(x|L) \approx \exp \left(-\left(d \frac{x}{L^{\frac{1}{c-1}}} \right)^{1-c} \right), \quad d = \left[\frac{1}{(c-1)\zeta(c-1)} \right]^{1/(1-c)}. \quad (15)$$

Therefore in this case, the average value of l_{\max} grows algebraically (and sub-linearly) with L , $\langle l_{\max} \rangle \propto L^{\frac{1}{c-1}}$. Besides, for $c > 2$, the number of domains is still extensive, $\approx L/\zeta(c-1)$ [24, 25] and therefore the

	$T > T_c$	$T = T_c$ $c \geq 2$ (II & III)	$T = T_c$ $1 < c < 2$ (I)	$T < T_c$
$\langle l_{\max} \rangle \approx$	$a_{\text{para}} \log L$	$a_{\text{crit}} L^{1/(c-1)}$	$A_1 L$	L
Cumulative dist. $P_1(x L) \approx$	$F_1[(x - b_L)/a]$	$F_2[x/L^{1/(c-1)}]$	$F_3(x/L)$	$F_4(L - x)$
	Gumbel	Fréchet	\neq i.i.d. case	\neq i.i.d. case

TABLE I. Summary of the main results for the average value $\langle l_{\max} \rangle$ and its cumulative distribution $P_1(x|L)$ in the different regions of the phase diagram depicted in Fig. 2. The amplitudes are given by $a_{\text{para}} = a$ [see Eq. (13)], $a_{\text{crit}} = d^{-1} \Gamma[(c - 2)/(c - 1)]$ [see Eq. (15)] and $A_1 \equiv A_1(c)$ is given in Eq. (16). The functions $F_1(y)$, $F_2(y)$, $F_3(y)$ and $F_4(y)$ – which are different in these four different cases – can be read off from Eqs. (12), (15), (17-18) and (22-23) respectively.

limiting distribution found here (15) coincides with the result of EVS for i.i.d. random variables with an algebraic PDF [4] (see also Appendix A), demonstrating that in this case the global constraint on the l_n 's in Eq. (7) is irrelevant. This is also in line with the results found for renewal processes in Ref. [29].

- (ii) If $c < 2$, the statistics of l_{\max} is quite different from the predictions of EVS for i.i.d. random variables. First we show that, in this case, $l_{\max} \sim L$ and in particular its first moment is given by

$$\langle l_{\max} \rangle \sim A_1(c) L, \quad A_1(c) = \frac{1}{c-1} \int_0^\infty \frac{\Gamma(1-c, x)}{\Gamma(1-c, x) - \Gamma(1-c)} dx, \quad (16)$$

where $\Gamma(\alpha, z) = \int_z^\infty x^{\alpha-1} e^{-x} dx$ is the incomplete gamma function. Note that $-\Gamma(1-c) > 0$ for $1 < c \leq 2$. Besides we show that in this case the limiting PDF of l_{\max} is given by (see Fig. 5 below)

$$P_1(x|L) \approx 1 - H_1\left(\frac{L}{x}\right), \quad (17)$$

where $H_1(u)$, which is defined for $u \geq 1$, obeys the following relation

$$\int_0^\infty e^{-wu} H_1(u) u^{c-2} du = \frac{\Gamma(c-1)}{w^{c-1}} \frac{\Gamma(1-c, w)}{\Gamma(1-c, w) - \Gamma(1-c)}. \quad (18)$$

The function $H_1(u)$ is a piece-wise analytic function, which has singularities at all integer values of $u > 1$ (while $H_1(u) = 0$ for $u \leq 1$). In particular, for $1 < u < 2$, $H_1(u)$ can be computed explicitly

$$H_1(u) = B(c) u^{2-c} (u-1)^{2c-2} {}_2F_1(1, c, 2c-1, 1-u), \quad 1 < u < 2, \quad (19)$$

with ${}_2F_1$ being the hypergeometric function and $B(c) = -\Gamma(c-1)/[\Gamma(1-c)\Gamma(2c-1)] > 0$. One can also check from Eq. (18) that $H_1(u) \rightarrow 1$ as $u \rightarrow \infty$, as it should (as $P_1(x|L) \rightarrow 0$ when $x \rightarrow 0$). For instance, for the special case $c = 3/2$, $H_1(u) = \sqrt{u} - 1$, for $1 < u < 2$. The asymptotic behaviors of the PDF $p_1(x|L)$, in the large L limit, are given in Eqs. (64) and (65). The non-trivial distribution $H_1(u)$ in Eq. (18) (see also Fig. 5 below) indicates that the global constraint is important in this case.

The extensivity of $\langle l_{\max} \rangle \propto L$ together with its non trivial PDF, exhibiting non analytic behaviors, is reminiscent of the results found for renewal processes, as in Eq. (11), when $f(l)$ exhibits heavy tails [27–29] – corresponding here to $c \leq 2$.

In this regime, one may wonder whether the largest domain is the only extensive one, or whether other domains are extensive. To answer this question, we have computed the statistics of the k^{th} largest domain, $l_{\max}^{(k)}$. We found that $l_{\max}^{(k)}$ is extensive for any finite k . In particular, its average is given by

$$\langle l_{\max}^{(k)} \rangle \sim A_k(c) L, \quad A_k(c) = \frac{1}{c-1} \int_0^\infty \left[\frac{\Gamma(1-c, x)}{\Gamma(1-c, x) - \Gamma(1-c)} \right]^k dx, \quad (20)$$

while its cumulative distribution $P_k(x|L) = \Pr.(l_{\max}^{(k)} \leq x)$ reads, for large L ,

$$P_k(x|L) \approx 1 - H_k\left(\frac{L}{x}\right), \quad (21)$$

$$\int_0^\infty \frac{e^{-wu}}{u^{2-c}} H_k(u) du = \frac{\Gamma(c-1)}{w^{c-1}} \left(\frac{\Gamma(1-c, w)}{\Gamma(1-c, w) - \Gamma(1-c)} \right)^k,$$

which, for $k = 1$, yields back the formula in Eq. (18). These results imply that for $c < 2$, there are, at the critical point, many macroscopic domains. Note that from Eq. (20) one easily checks that $\sum_{k=1}^\infty \langle l_{\max}^{(k)} \rangle = L$. Besides, from Eq. (21), one can show that $H_k(u) = 0$ for $0 < u \leq k$ (as the k -th largest domain is necessarily *smaller* than L/k), while $H_k(u) \rightarrow 1$ as $u \rightarrow \infty$. As for $k = 1$, one can also show that $H_k(u)$ has singularities at every integer values of $u \geq k$. Note that the k -th longest excursion for renewal processes (11), and $f(l) \sim l^{-3/2}$, was recently studied in Ref. [30].

- $T < T_c$: in this case it is more convenient to focus on the PDF $p_1(x|L) = P_1(x|L) - P_1(x-1|L) = \Pr.(l_{\max} = x)$. We find that, for large L , keeping x fixed, it reads

$$p_1(x|L) \approx f_{\text{ferro}}(y = L - x), \quad (22)$$

where the generating function of the scaling function $f_{\text{ferro}}(y)$, with $y \in \mathbb{N}$, is given by (see also Fig. 4 below)

$$\sum_{y=0}^\infty z^y f_{\text{ferro}}(y) = \left(\frac{1 - e^{-\beta \Delta \zeta(c)}}{1 - e^{-\beta \Delta \text{Li}_c(z)}} \right)^2. \quad (23)$$

The asymptotic behaviors of $f_{\text{ferro}}(y)$ can easily be extracted from this expression (23) and they are given in Eq. (49) below. Note that Eq. (22) implies that for large L , the maximum domain size is given by $l_{\max} \approx L$. Besides the limiting distribution $f_{\text{ferro}}(x)$ is actually quite different from the standard limiting distributions known from the EVS of i.i.d. random variables, which shows that the global constraint among the l_n 's (7) is actually important in the ferromagnetic phase. Interestingly, the limiting distribution $f_{\text{ferro}}(x)$ has an algebraic tail [see Eq. (49)], $f_{\text{ferro}}(x) \propto x^{-c}$. This indicates that $\langle l_{\max} \rangle - L \approx \mathcal{O}(1)$ for $c \geq 2$ while $\langle l_{\max} \rangle - L \sim \mathcal{O}(L^{2-c})$ for $1 < c < 2$ (and a logarithmic growth for $c = 2$). In this case, one can show that the size of the next maxima $l_{\max}^{(k)}$, for $k \geq 2$ are all of order 1, $l_{\max}^{(k)} \approx \mathcal{O}(1)$. Their distribution, that depends on k , is rather cumbersome and is not given here.

To summarize, the general picture is that in the paramagnetic phase domains are small, and hence correlations – which emerge due to the global constraint (3) – are essentially negligible. In the ferromagnetic phase the maximal domain consists of almost all of the sites of the chain, and the typical fluctuations are of order $\mathcal{O}(1)$. At the transition, if $c > 2$ the domains are again small (sub-extensive) and the effect of correlations is negligible, but for $c < 2$ the maximal domain is extensive and the correlations are relevant. These results are summarized in Table I.

B. Derivation of the results

The starting point of our analytical computations is an exact expression for the cumulative distribution $P_1(x|L) = \text{Pr.}(l_{\max} \leq x)$ of the largest domain $l_{\max} = \max_{1 \leq n \leq N} l_n$ in the TIDSI model. It is simply obtained by summing up the joint PDF of the domains in Eq. (7) over the lengths l_n 's from 1 to x (for a fixed value of the number N of domains) and then by summing over all possible values of N . This yields the following ratio:

$$P_1(x|L) = \frac{W_0(x|L)}{Z(L)}, \quad (24)$$

where $Z(L)$ is the partition function given in Eq. (8) and $W_0(x|L)$ is thus given by

$$W_0(x|L) = \sum_{N=1}^{\infty} \sum_{l_1=1}^x \dots \sum_{l_N=1}^x \prod_{n=1}^N \frac{e^{-\beta\Delta}}{l_n^c} \delta_{\sum_{n=1}^N l_n, L}. \quad (25)$$

Obviously, $Z(L) = \lim_{x \rightarrow \infty} W_0(x, L)$. Similarly, to compute the cumulative distribution of the k -th largest domain $l_{\max}^{(k)}$, $P_k(x|L) = \text{Pr}\left(l_{\max}^{(k)} \leq x\right)$, it is useful to first introduce an auxiliary probability $W_p(x|L)/Z(L)$, with an integer $p \geq 0$, which denotes the probability that there are exactly p domains whose size are bigger than x . For the event that the k -th largest domain has length less than or equal to x to occur, there must be *at most* $k-1$ domains with lengths bigger or equal to x (see for instance Ref. [31]). The cumulative probability $P_k(x|L)$ can then be written as

$$P_k(x|L) = \frac{1}{Z(L)} \sum_{p=0}^{k-1} W_p(x|L), \quad (26)$$

where $W_0(x, L)$ is given in Eq. (25) while, for $p \geq 1$, $W_p(x|L)$ is computed straightforwardly as

$$W_p(x|L) = \sum_{N=p}^{\infty} e^{-N\beta\Delta} \binom{N}{p} \sum_{l_1=x+1}^{\infty} \dots \sum_{l_p=x+1}^{\infty} \sum_{l_{p+1}=1}^x \dots \sum_{l_N=1}^x \prod_{n=1}^N \frac{1}{l_n^c} \delta_{\sum_{n=1}^N l_n, L}, \quad p \geq 1 \quad (27)$$

where the binomial coefficient $\binom{N}{p}$ is a simple combinatorial factor counting the number of different ways to choose these p largest domains among N .

We start by analyzing the distribution of the largest domain, $P_1(x|L)$, above, at and below the critical temperature T_c . The difficulty with evaluating expressions such as (25) and (27) comes from the constraint over the domain sizes. To handle such sums, it is customary, see for instance [25, 26], to work with the corresponding generating functions with respect to (w.r.t.) L (in the language of statistical physics, this amounts to shift from the canonical to the grand-canonical ensemble). One obtains

$$\begin{aligned} \widetilde{W}_0(x, z) &= \sum_{L=1}^{\infty} W_0(x|L) z^L \\ &= \sum_{N=1}^{\infty} \prod_{n=1}^N \left(\sum_{l=1}^x \frac{e^{-\beta\Delta} z^l}{l^c} \right) = \frac{e^{-\beta\Delta} \Phi_c(z, x)}{1 - e^{-\beta\Delta} \Phi_c(z, x)}, \end{aligned} \quad (28)$$

where the function $\Phi_c(z, x)$ is given by

$$\Phi_c(z, x) = \sum_{l=1}^x \frac{z^l}{l^c}. \quad (29)$$

These explicit and exact formulae in Eqs. (28) and (29) are our starting point to extract the large L behavior of $W_0(x|L)$, via the Cauchy's inversion formula

$$W_0(x|L) = \frac{1}{2\pi i} \oint \frac{1}{z^{L+1}} \widetilde{W}_0(x, z) dz, \quad (30)$$

where the integration contour runs around the origin and does not contain any singularities of $\widetilde{W}_0(x, z)$. Eventually one obtains $P_1(x|L)$ from Eq. (24), in the different regions of the phase diagram.

Similarly, the generating function of $W_p(x|L)$ can also be expressed as

$$\begin{aligned} \widetilde{W}_p(x, z) &= \sum_{L=1}^{\infty} W_p(x|L) z^L \\ &= \sum_{N=p}^{\infty} e^{-N\beta\Delta} \binom{N}{p} [\text{Li}_c(z) - \Phi_c(z, x)]^p [\Phi_c(z, x)]^{N-p}, \quad p \geq 1, \end{aligned} \quad (31)$$

where $\text{Li}_c(z) = \lim_{x \rightarrow \infty} \Phi_c(z, x)$ denotes the polylogarithm function

$$\text{Li}_c(z) = \sum_{l=1}^{\infty} \frac{z^l}{l^c}. \quad (32)$$

It is straightforward to perform the sum over N in Eq. (31) to obtain

$$\widetilde{W}_p(x, z) = \frac{e^{-p\beta\Delta} [\text{Li}_c(z) - \Phi_c(z, x)]^p}{[1 - e^{-\beta\Delta} \Phi_c(z, x)]^{p+1}}, \quad p \geq 1. \quad (33)$$

Note that this expression is valid only for $p \geq 1$, while for $p = 0$ Eq. (28) holds. Finally, $W_p(x|L)$ for $p \geq 1$ can also be obtained via Cauchy's inversion formula

$$W_p(x|L) = \frac{1}{2\pi i} \oint \frac{1}{z^{L+1}} \widetilde{W}_p(x, z) dz, \quad (34)$$

where the integration contour runs around the origin and does not contain any singularities of $\widetilde{W}_p(x, z)$. Eventually one obtains $P_k(x|L)$ from Eq. (26), in the different regions of the phase diagram.

1. The largest domain in the paramagnetic phase ($T > T_c$)

In this regime $e^{-\beta\Delta} \zeta(c) < 1$ [see Eq. (9)] and to compute $W_0(x, L)$ from Eq. (30), for large L , one notices that, for fixed x , $\widetilde{W}_0(x, z)$ has a simple pole at $z^*(x)$ [see Eq. (28)] given by

$$1 - e^{-\beta\Delta} \Phi_c(z^*(x), x) = 0. \quad (35)$$

For $T > T_c$, $z^*(x) < 1$ for all finite x [this can be checked from Eq. (9)]. Because of the existence of this pole the integral in (30) can be evaluated to leading order in the large L limit as

$$W_0(x|L) \approx [z^*(x)]^{-L}.$$

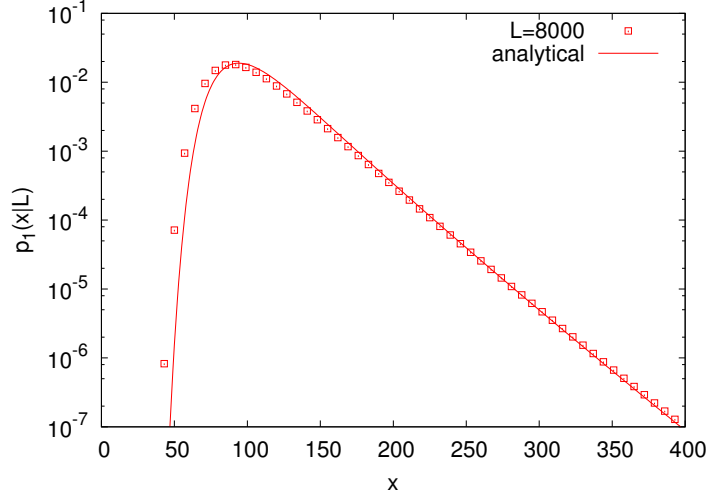


FIG. 3. Log-linear plot of $p_1(x|L)$ for $c = 3/2$ and $e^{-\beta\Delta} = 0.5$ (hence in the paramagnetic phase). The square symbols correspond to a numerical evaluation of $p_1(x|L)$ for $L = 8000$ (see Appendix C for details) while the solid line corresponds to the exact formula given in Eq. (39).

In particular, $Z(L) = \lim_{x \rightarrow \infty} W_0(x|L) = (z^*)^{-L}$ where $z^* \equiv z^*(x \rightarrow \infty)$. Using that $\Phi_c(z, x \rightarrow \infty) = \text{Li}_c(z)$, Eq. (35) implies that z^* satisfies Eq. (14). And therefore

$$P_1(x) = \frac{W_0(x|L)}{Z(L)} \approx \left(\frac{z^*}{z^*(x)} \right)^L. \quad (36)$$

We now compute $z^*(x)$ for large x from Eq. (35). This is done by using the large x expansion of $\Phi_c(z, x)$:

$$\begin{aligned} \Phi_c(z, x) &= \text{Li}_c(z) - \sum_{l=x+1}^{\infty} \frac{z^l}{l^c} = \text{Li}_c(z) - z^{x+1} \sum_{l=0}^{\infty} \frac{z^l}{(x+1+l)^c} \\ &= \text{Li}_c(z) - \frac{1}{1-z} \frac{z^{x+1}}{x^c} (1 + \mathcal{O}(x^{-1})). \end{aligned} \quad (37)$$

By using this asymptotic expansion (37), we find that $z^*(x)$, which is solution of Eq. (35), admits the large x expansion:

$$z^*(x) = z^* + \frac{1}{1-z^*} \frac{1}{\text{Li}_{c-1}(z^*)} \frac{z^{*x+2}}{x^c} (1 + \mathcal{O}(x^{-1})), \quad (38)$$

where we recall that z^* satisfies Eq. (14). From Eq. (36) together with Eq. (38) one obtains:

$$P_1(x|L) \sim \left(1 + \frac{1}{1-z^*} \frac{1}{\text{Li}_{c-1}(z^*)} \frac{z^{*x+1}}{x^c} \right)^{-L}. \quad (39)$$

In the large L limit, Eq. (39) eventually leads to the Gumbel distribution announced in Eq. (12).

In Fig. 3 we show a comparison between a numerical estimate of $p_1(x|L)$ and the exact analytical formula derived from Eq. (39). Note that the small discrepancy observed for small values of x is a finite L effect. For very large L , one expects that this formula (39) converges to the Gumbel form given in Eq. (12). Note that, for finite L , one expects to observe rather strong finite size effects, as this is the case for the EVS of i.i.d. random variables [32].

2. *The largest domain in the ferromagnetic phase ($T < T_c$)*

We start by evaluating the partition function $Z(L)$ in Eq. (8). Its generating function $\tilde{Z}(z)$ is given by

$$\tilde{Z}(z) = \lim_{x \rightarrow \infty} \tilde{W}_0(x, z) = \frac{e^{-\beta\Delta} \text{Li}_c(z)}{1 - e^{-\beta\Delta} \text{Li}_c(z)}, \quad (40)$$

from which one can show that the large L behavior of $Z(L)$ is controlled by the branch point at $z = 1$ of $\tilde{Z}(z)$. Indeed, here, and in the following, we will use the asymptotic behavior of the polylogarithm function,

$$\text{Li}_c(z) = \zeta(c) + (1-z)^{c-1} [\Gamma(1-c) + \mathcal{O}((1-z)^3)] + (1-z) [-\zeta(c-1) + \mathcal{O}(1-z)] . \quad (41)$$

From this asymptotic behavior (41), one obtains the behavior of $\tilde{Z}(z)$ for z close 1 as

$$\tilde{Z}(z) \sim \frac{e^{-\beta\Delta}}{1 - e^{-\beta\Delta} \zeta(c)} + \frac{e^{-\beta\Delta}}{(1 - e^{-\beta\Delta} \zeta(c))^2} \Gamma(1-c) (1-z)^{c-1} (1 + \mathcal{O}(1-z)) + \text{regular terms} . \quad (42)$$

From Eq. (42), one thus obtains the large L behavior of $Z(L)$ as

$$Z(L) \approx \frac{e^{-\beta\Delta}}{(1 - e^{-\beta\Delta} \zeta(c))^2} L^{-c} . \quad (43)$$

In the ferromagnetic phase, it is more convenient to compute the PDF of l_{\max} (instead of the cumulative distribution), as in the case of ZRP [26]. It reads

$$p_1(x|L) = \Pr.(l_{\max} = x) = P_1(x|L) - P_1(x-1|L) = \frac{1}{Z(L)} [W_0(x|L) - W_0(x-1|L)] . \quad (44)$$

Using the expression of $W_0(x|L)$ in Eqs. (30) and (28) one obtains

$$p_1(x|L) = \frac{e^{-\beta\Delta}}{Z(L)} \frac{1}{2\pi i} \oint \frac{1}{z^{L+1}} \frac{z^x}{x^c} \frac{1}{1 - e^{-\beta\Delta} \Phi_c(z, x)} \frac{1}{1 - e^{-\beta\Delta} \Phi_c(z, x-1)} dz . \quad (45)$$

Setting $x = L - y$ in Eq. (45) one finds

$$p_1(L-y|L) = e^{-\beta\Delta} \frac{(L-y)^{-c}}{Z(L)} \frac{1}{2\pi i} \oint \frac{1}{z^{y+1}} \frac{1}{1 - e^{-\beta\Delta} \Phi_c(z, L-y)} \frac{1}{1 - e^{-\beta\Delta} \Phi_c(z, L-y-1)} dz . \quad (46)$$

Therefore using the asymptotic behavior of $Z(L)$ in (43), one obtains the limiting expression of $p_1(L-y|L)$ in Eq. (46), for fixed y and $L \rightarrow \infty$ as

$$p_1(L-y|L) \approx (1 - e^{-\beta\Delta} \zeta(c))^2 \frac{1}{2\pi i} \oint \frac{1}{z^{y+1}} \frac{1}{[1 - e^{-\beta\Delta} \text{Li}_c(z)]^2} dz . \quad (47)$$

Therefore one has

$$p_1(x|L) = p_1(L-y|L) \approx f_{\text{ferro}}(y) = (1 - e^{-\beta\Delta} \zeta(c))^2 \frac{1}{2\pi i} \oint \frac{1}{z^{y+1}} \frac{1}{[1 - e^{-\beta\Delta} \text{Li}_c(z)]^2} dz . \quad (48)$$

This is equivalent to the expression given in Eq. (23), upon using the Cauchy's inversion formula. It is easy to derive now the asymptotic behavior of the function $f_{\text{ferro}}(y)$ from Eq. (23). For example, taking the limit $z \rightarrow 0$ in Eq. (23) and using $\text{Li}_c(0) = 0$, one obtains $f_{\text{ferro}}(0) = (1 - e^{-\beta\Delta} \zeta(c))^2$. In contrast, by taking the $z \rightarrow 1$ limit and using the asymptotic properties of $\text{Li}_c(z)$ in Eq. (41), it is easy to show that $f_{\text{ferro}}(y) \sim A_{\text{ferro}}/y^c$ for large y (where

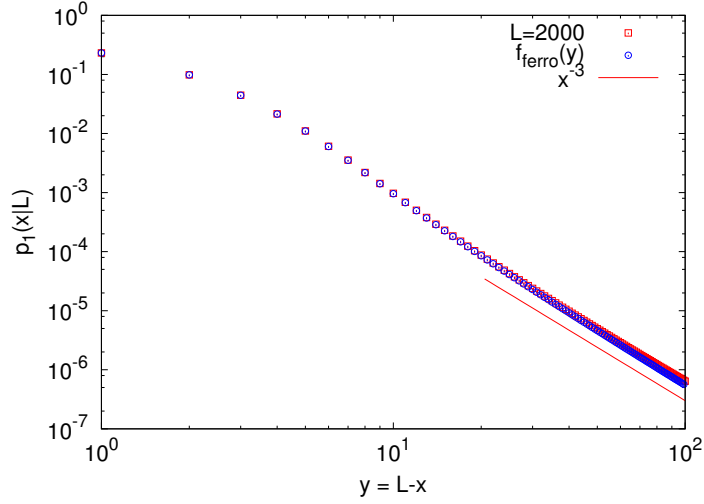


FIG. 4. Plot of $p_1(x|L)$ for $c = 3$ and $e^{-\beta\Delta} = 0.2$ (hence in the ferromagnetic phase). The square symbols correspond to a numerical evaluation of $p_1(x|L)$ for $L = 2000$ (see Appendix C for details) while the circular symbols correspond to the exact limiting distribution $f_{\text{ferro}}(y)$ obtained by expanding the right hand side of Eq. (23) in powers of z . The slight discrepancy between the numerical and the exact asymptotic results is a finite L effect. The solid line is a guide to the eyes indicating the expected algebraic behavior $\propto x^{-c}$, see Eq. (49).

L has been sent to infinity already), where $A_{\text{ferro}} = 2e^{-\beta\Delta}/(1 - e^{-\beta\Delta}\zeta(c))$. The asymptotic behaviors of $f_{\text{ferro}}(y)$ can thus be summarized as follows

$$f_{\text{ferro}}(y) \approx \begin{cases} (1 - e^{-\beta\Delta}\zeta(c))^2, & y \rightarrow 0, \\ \frac{A_{\text{ferro}}}{y^c}, & y \rightarrow \infty. \end{cases} \quad (49)$$

In Fig. 4 we show a comparison between a numerical evaluation of $p_1(x|L)$ for large $L = 2000$ and the exact asymptotic result in Eqs. (22) and (23).

3. The largest domain at the critical point ($T = T_c$), for $1 < c < 2$

We recall that in this case $e^{\beta_c\Delta} = \zeta(c)$, see Eq. (9). In this case the pole $z^*(x) < 1$ for finite x converges to the branch-cut at $z = 1$ as $x \rightarrow \infty$, which then dominates the integral in Eq. (30). We thus set $z = e^{-s}$, and evaluate $\Phi_c(e^{-s}, x)$ when $s \rightarrow 0$. It is then convenient to rewrite $\Phi_c(e^{-s}, x)$ as

$$\begin{aligned} \Phi_c(e^{-s}, x) &= \sum_{l=1}^x \frac{e^{-sl}}{l^c} \\ &= \text{Li}_c(e^{-s}) - \sum_{l=x+1}^{\infty} \frac{e^{-sl}}{l^c}. \end{aligned} \quad (50)$$

We recall the asymptotic behavior of the polylogarithm function [see Eq. (41)],

$$\text{Li}_c(e^{-s}) = \zeta(c) + s^{c-1} [\Gamma(1-c) + \mathcal{O}(s^3)] + s [-\zeta(c-1) + \mathcal{O}(s)] , \quad (51)$$

whose leading behavior thus depends on whether $c < 2$ or $c > 2$. Besides, in the limit $s \rightarrow 0$, the discrete sums over l in Eq. (50) can be replaced, to leading order, by integrals. Therefore, in the limit $s \rightarrow 0$, $x \rightarrow \infty$ keeping sx fixed one obtains (using Eq. (51) for $c < 2$ here)

$$\Phi_c(e^{-s}, x) \approx \zeta(c) + s^{c-1} [\Gamma(1-c) - \Gamma(1-c, sx)] , \quad (52)$$

where we recall that $\Gamma(\alpha, z) = \int_z^\infty x^{\alpha-1} e^{-x} dx$. Using this small s behavior (52) in the expression for $\widetilde{W}_0(x, e^{-s})$ in Eq. (28), one obtains

$$\widetilde{W}_0(x, e^{-s}) \sim \frac{\zeta(c)}{s^{c-1}} \frac{1}{\Gamma(1-c, sx) - \Gamma(1-c)} , \text{ for } s \rightarrow 0, x \rightarrow \infty, \text{ keeping } sx \text{ fixed} , \quad (53)$$

where we have used $e^{-\beta_c \Delta} \zeta(c) = 1$, see Eq. (9). This formula in Eq. (53), evaluated in the limit $x \rightarrow \infty$ (for finite s) yields, using $Z(L) = \lim_{x \rightarrow \infty} W_0(x|L)$

$$\sum_{L=1}^{\infty} e^{-sL} Z(L) \approx \int_0^{\infty} e^{-sL} Z(L) dL \approx -\frac{\zeta(c)}{\Gamma(1-c)} s^{1-c} , \quad (54)$$

which yields the large L behavior of the partition function $Z(L)$

$$Z(L) \approx -\frac{\zeta(c)}{\Gamma(1-c)\Gamma(c-1)} L^{c-2} , \quad L \rightarrow \infty . \quad (55)$$

On the other hand, by rewriting the small s behavior of $\widetilde{W}_0(x, e^{-s})$ in Eq. (53) as

$$\widetilde{W}_0(x, e^{-s}) = -\frac{\zeta(c)}{\Gamma(1-c)s^{c-1}} \left(1 - \frac{\Gamma(1-c, sx)}{\Gamma(1-c, sx) - \Gamma(1-c)} \right) \quad (56)$$

we obtain that $W_0(x|L)$ takes the following scaling form, for $L \rightarrow \infty$, $x \rightarrow \infty$ keeping x/L finite:

$$W_0(x|L) \sim L^{c-2} \left[-\frac{\zeta(c)}{\Gamma(1-c)\Gamma(c-1)} \right] \left(1 - H_1\left(\frac{L}{x}\right) \right) . \quad (57)$$

Dividing by $Z(L)$ given in Eq. (55) one then gets

$$P_1(x|L) = \frac{W_0(x|L)}{Z(L)} = 1 - H_1\left(\frac{L}{x}\right) , \quad (58)$$

where the scaling function $H_1(L/x)$ satisfies

$$\sum_{L=1}^{\infty} e^{-sL} L^{c-2} H_1\left(\frac{L}{x}\right) \approx \frac{\Gamma(1-c, sx)}{\Gamma(1-c, sx) - \Gamma(1-c)} . \quad (59)$$

This equation holds in the scaling limit where $L \rightarrow \infty$, $x \rightarrow \infty$ keeping the ratio L/x fixed. Equivalently, in the Laplace space, this corresponds to taking $s \rightarrow 0$, $x \rightarrow \infty$, keeping sx finite. In the limit $s \rightarrow 0$, the discrete sum over L can be replaced by an integral over the continuous variable L . Performing the change of variable $u = L/x$ in that integral yields the relation for $H_1(u)$ announced in Eq. (18):

$$\int_0^{\infty} e^{-wu} H_1(u) u^{c-2} du = \frac{\Gamma(c-1)}{w^{c-1}} \frac{\Gamma(1-c, w)}{\Gamma(1-c, w) - \Gamma(1-c)} . \quad (60)$$

It turns out that this expression can be inverted explicitly in the range $1 < u < 2$ (see Appendix B for details). One obtains

$$H_1(u) = B(c) u^{2-c} (u-1)^{2c-2} {}_2F_1(1, c, 2c-1, 1-u), \quad 1 < u < 2, \quad (61)$$

with ${}_2F_1$ being the hypergeometric function and $B(c) = -\Gamma(c-1)/[\Gamma(1-c)\Gamma(2c-1)] > 0$, as announced in the introduction in Eq. (19). In particular, for $u \rightarrow 1$, $H_1(u)$ behaves as

$$H_1(u) \approx B(c)(u-1)^{2c-2}, \quad u \rightarrow 1. \quad (62)$$

From the cumulative distribution in Eq. (58), one can obtain the PDF of l_{\max} as

$$p_1(x|L) \approx \frac{\partial}{\partial x} [1 - H_1(L/x)] = \frac{L}{x^2} H_1'(L/x). \quad (63)$$

Multiplying both sides by L one gets

$$L p_1(x|L) \approx g\left(\frac{x}{L}\right), \quad \text{where } g(y) = \frac{1}{y^2} H_1'\left(\frac{1}{y}\right). \quad (64)$$

From the asymptotic behavior of $H_1(u)$ in Eq. (62) when $u \rightarrow 1$, one obtains the behavior of $g(y)$ for $y \rightarrow 1$, as $g(y) \approx 2B(c)(c-1)(1-y)^{2c-3}$. On the other hand, in the opposite limit $y \rightarrow 0$, we need to investigate the large u asymptotics of $H_1(u)$ in Eq. (60). In this limit, we need to study the poles of $H_1(u)$, i.e., the zeros of $w^{c-1}[\Gamma(1-c, w) - \Gamma(1-c)]$, which are denoted by s_k . These zeroes are such that $s_{\pm k} = -\alpha_k + i\beta_k$ with a negative real part ($\alpha_k > 0$, for all k) and $0 < \alpha_0 < \alpha_1 < \alpha_2 < \dots$. Furthermore, $s_0 = -\alpha_0$ is the only real zero (i.e., $\beta_0 = 0$) [33]. Therefore in the large u limit, one has $1 - H_1(u) \propto e^{-\alpha_0 u}$ and the amplitude can be computed explicitly by evaluating the residue of the integrand at $w = -\alpha_0$. Finally, the asymptotic behaviors of $g(y)$ can be summarized as follows

$$g(y) \approx \begin{cases} \gamma_0 e^{-\alpha_0/y} y^{c-4} \left(1 - \frac{2-c}{\alpha_0} y\right) + \mathcal{O}(e^{-\alpha_1/y}), & y \rightarrow 0, \\ \gamma_1 (1-y)^{2c-3} + \mathcal{O}((1-y)^{2c-2}), & y \rightarrow 1, \end{cases} \quad (65)$$

where $\gamma_0 = \pi \alpha_0^2 e^{-\alpha_0} / [(c-1) \sin(\pi(c-1))]$ and $\gamma_1 = 2(c-1)B(c)$ and where $-\alpha_0$ is the single negative real zero of $\Gamma(1-c, w) - \Gamma(1-c)$ as a function of real w . Note also that, by looking at the asymptotic behavior of $g(y)$ for $y \rightarrow 1$ in Eq. (65), one observes that $c = 3/2$ appears as a kind of "transition" point. For $c < 3/2$, $g(y)$ is diverging when $y \rightarrow 1$ while it is vanishing for $c > 3/2$. Exactly at $c = 3/2$, $g(y) = 1/(2y^{3/2})$ and in this case $g(y \rightarrow 1) = 1/2$.

In Fig. 5 (left panel) we show a scaled plot of the PDF of l_{\max} , $L p_1(x|L)$ as a function of $y = x/L$ for $L = 100$ and $L = 1000$ at criticality and for $c = 1.3$. This plot shows a very good agreement with the scaling form predicted in Eq. (64) $L p_1(x|L) \approx g(y = x/L)$. This plot also shows clearly the singularity of $p_1(x|L)$ for $x = L/2$, a feature which is commonly observed in the PDF of such extreme quantities in related models [27–29]. In the right panel of Fig. 5 we show that our numerical data (for $L = 4000$) are in very good agreement with our exact formula (the solid line) valid for $x/L \geq 1/2$, given in Eqs. (64) and (61). Furthermore, we show that the asymptotic behavior of $g(y)$ for $y \rightarrow 0$ in Eq. (65) – plotted as a dotted line in Eq. (65) – provides a very good estimate in the whole interval $[0, 1/2]$.

To conclude this section, we compute the average value $\langle l_{\max} \rangle$, which is conveniently written as

$$\langle l_{\max} \rangle = \sum_{x=1}^{\infty} [1 - P_1(x|L)] = \frac{1}{Z(L)} \sum_{x=1}^{\infty} [Z(L) - W_0(x|L)]. \quad (66)$$

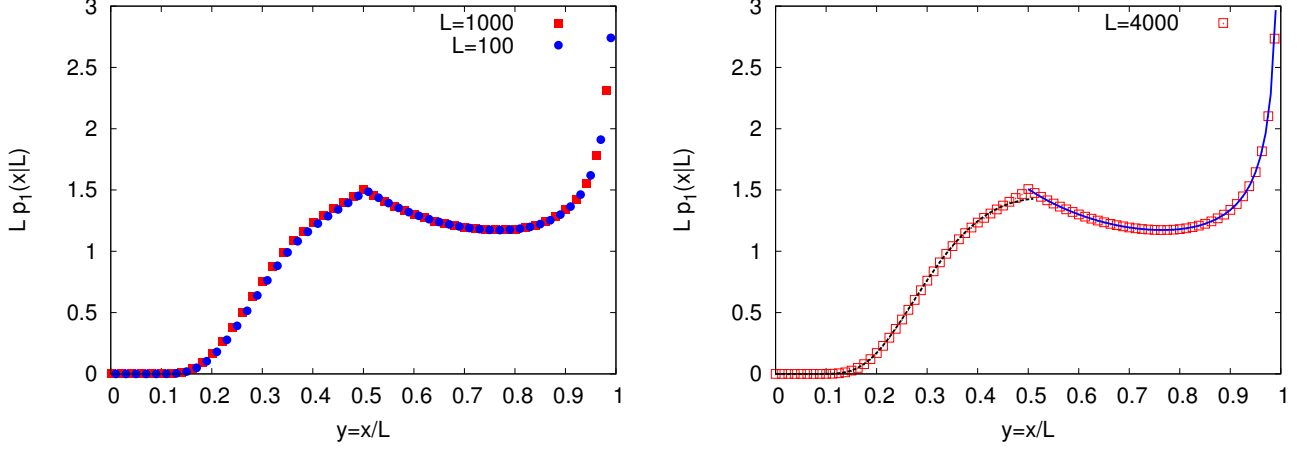


FIG. 5. **Left:** Scaled plot of the PDF of l_{\max} , $L p_1(x/L)$ as a function of x/L for $L = 100$ and $L = 1000$ at criticality and for $c = 1.3$. The good collapse of the data (obtained from numerical simulations, [see Appendix C for details]), for these two different values of L , corroborate the scaling form given in Eq. (64). The singularity for $x/L = 1/2$ is clearly visible on this plot, while other singularities (of higher order and hence not visible on this plot) also exist for $x/L = 1/k$, with $k = 3, 4, \dots$ **Right:** Scaled plot of the PDF of l_{\max} , $L p_1(x/L)$ as a function of x/L for $L = 4000$ at criticality and for $c = 1.3$. The squared symbols correspond to a numerical evaluation of $p_1(x/L)$ while the blue solid line, for $x/L \geq 1/2$ corresponds to the exact result given in Eqs. (64) and (61). The dotted line for $y < 1/2$ corresponds to the asymptotic behavior for $y \rightarrow 0$, given in Eq. (65) (and in this case $\alpha_0 \approx 1.582$).

From the results obtained in Eqs. (54) and (56), one finds that the generating function of the numerator is given by

$$\sum_{L=1}^{\infty} e^{-sL} \sum_{x=1}^{\infty} [Z(L) - W_0(x|L)] \approx -\frac{\zeta(c)}{\Gamma(1-c)} \frac{1}{s^c} \int_0^{\infty} \frac{\Gamma(1-c, u)}{\Gamma(1-c, u) - \Gamma(1-c)} du, \quad s \rightarrow 0. \quad (67)$$

These relations (66) and (67), together with the expression for $Z(L)$ in Eq. (55), lead to the result for $\langle l_{\max} \rangle$ announced in Eq. (16).

4. The largest domain at the critical point ($T = T_c$), for $c > 2$

In this case, $\Phi_c(e^{-s}, x)$ behaves, for $s \rightarrow 0$, as

$$\Phi_c(e^{-s}, x) = \sum_{l=1}^x \frac{e^{-sl}}{l^c} = \text{Li}_c(e^{-s}) - \sum_{l=x+1}^{\infty} \frac{e^{-sl}}{l^c}. \quad (68)$$

For $c > 2$, the first term behaves as $\text{Li}_c(e^{-s}) = \zeta(c) - s\zeta(c-1) + o(s)$ [see Eq. (41)]. On the other hand, when $s \rightarrow 0$ the discrete sum over l can be replaced by an integral over l which, for $s \rightarrow 0$ and $x \rightarrow \infty$ behaves simply as

$$\sum_{l=x+1}^{\infty} \frac{e^{-sl}}{l^c} \approx \frac{x^{1-c}}{c-1}. \quad (69)$$

Therefore one has the asymptotic behavior

$$\Phi_c(e^{-s}, x) \approx \zeta(c) - s\zeta(c-1) - \frac{x^{1-c}}{c-1}. \quad (70)$$

It thus follows from Eqs. (28) and (70) that

$$\widetilde{W}_0(x, e^{-s}) \approx \frac{\zeta(c)}{\zeta(c-1)} \frac{1}{s + d x^{1-c}} \quad (71)$$

where $d = 1/[(c-1)\zeta(c-1)]$, from which it follows that, for large L ,

$$W_0(x|L) \sim e^{-d L x^{1-c}}. \quad (72)$$

The partition function $Z(L) = W_0(x \rightarrow \infty|L) \approx 1$ for large L and $c > 2$. Hence $P_1(x|L) = W_0(x|L)/Z(L)$ tends to the Fréchet distribution announced in Eq. (15).

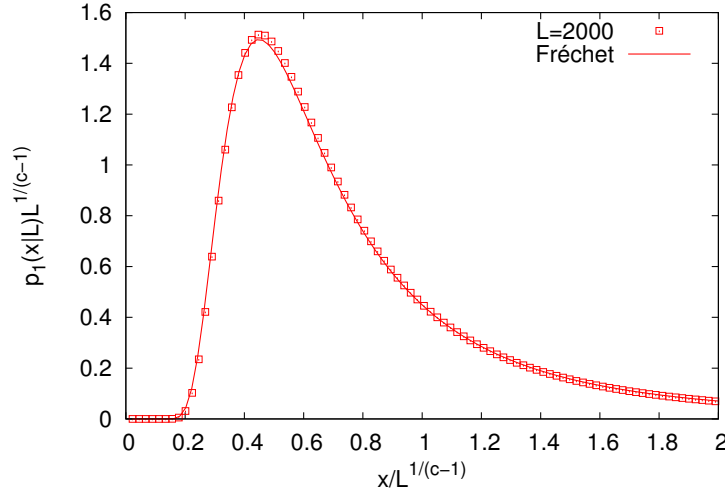


FIG. 6. Scaled plot of $p_1(x|L) L^{1/(c-1)}$ as a function of $x/L^{1/(c-1)}$, for $L = 2000$, according to Eq. (15) – we recall that $p_1(x|L) = P_1(x|L) - P_1(x-1|L)$ – for $c = 3$ at the critical temperature [see Eq. (9)]. The solid line corresponds to the Fréchet distribution with parameters specified in Eq. (15).

In Fig. 6, we show a scaled plot of the PDF of l_{\max} , $p_1(x|L) L^{1/(c-1)}$ as a function of $x/L^{1/(c-1)}$ evaluated numerically for $L = 2000$. We see that the data are quite well described by our exact analytical prediction given in Eq. (15).

5. The k^{th} largest domain

The starting point for the analysis of the cumulative distribution $P_k(x|L)$ of the k -th largest domain is the expression given in Eq. (26) in terms of the probability $W_p(x|L)/Z(L)$ (27) that there are exactly p domains

whose size are larger than x . As done before for $P_1(x|L)$, it is convenient to study the generating function of $W_p(x|L)$ with respect to L , which reads, for $p \geq 1$

$$\begin{aligned}\widetilde{W}_p(x, z) &= \sum_{L=1}^{\infty} W_p(x|L) z^L \\ &= \sum_{N=p}^{\infty} e^{-N\beta\Delta} \binom{N}{p} [\text{Li}_c(z) - \Phi_c(z, x)]^p [\Phi_c(z, x)]^{N-p}.\end{aligned}\quad (73)$$

It is straightforward to perform the sum over N to obtain

$$\widetilde{W}_p(x, z) = \frac{e^{-p\beta\Delta} [\text{Li}_c(z) - \Phi_c(z, x)]^p}{[1 - e^{-\beta\Delta}\Phi_c(z, x)]^{p+1}}. \quad (74)$$

This formula (74) is exact in the whole phase diagram and we now focus on the critical line, where $T = T_c$, and restrict our attention to the case $c < 2$ where one expects that $P_k(x)$ will be described by a non-trivial distribution, i.e. different from the one predicted by the EVS of i.i.d. sequences. In this case, we set $z = e^{-s}$ and the large L behavior of $W_p(x|L)$ is governed by the behavior of $\widetilde{W}_p(x, e^{-s})$ when $s \rightarrow 0$. In the scaling limit, $s \rightarrow 0$, $x \rightarrow \infty$, keeping the product sx fixed, one obtains, using the expansion of $\Phi_c(e^{-s}, x)$ in Eq. (52) together with $\text{Li}_c(e^{-s}) \approx \zeta(c) + \Gamma(1-c)s^{c-1}$:

$$\widetilde{W}_p(x, e^{-s}) \approx \frac{\zeta(c)}{s^{c-1}} \frac{[\Gamma(1-c, sx)]^p}{[\Gamma(1-c, sx) - \Gamma(1-c)]^{p+1}}. \quad (75)$$

Note that setting $p = 0$ in this formula (75) yields back the result obtained above for $\widetilde{W}_0(x, e^{-s})$ in the same scaling limit (53). The probability $P_k(x)$ is obtained by summing up the probabilities $W_p(x|L)/Z(L)$ for $0 \leq p \leq k-1$. From Eq. (75), one obtains straightforwardly

$$\sum_{p=0}^{k-1} \widetilde{W}_p(x, e^{-s}) = -\frac{\zeta(c)}{s^{c-1}\Gamma(1-c)} \left(1 - \left[\frac{\Gamma(1-c, sx)}{\Gamma(1-c, sx) - \Gamma(1-c)} \right]^k \right). \quad (76)$$

From this expression (76) together with Eq. (26), by performing the same manipulations as for $k = 1$, see Eqs. (56)-(59), one arrives at the expression for $P_k(x|L)$ given in Eq. (21). Finally, the computation of the average value $\langle l_{\max}^{(k)} \rangle$ can be performed along the same lines as for $k = 1$ [see Eqs. (66), (67)]. Using Eq. (76), this yields the result announced in Eq. (20).

IV. RELATION TO OTHER MODELS

A. Relation to the inverse distance squared Ising model

As mentioned in the introduction, MOTs appear in several apparently unrelated contexts. One of the first models which was studied in this context is the one-dimensional Ising model with interactions decaying as r^{-2} , named here the inverse distance squared Ising (IDSI) model. The IDSI is defined, much like the TIDSI, on a spin chain of size L , with the Hamiltonian

$$\mathcal{H} = - \sum_{i < j} J(i-j) \sigma_i \sigma_j, \quad (77)$$

$$J(r) \approx Cr^{-2}. \quad (78)$$

Thouless [7] was the first to suggest that this model exhibits a discontinuous phase transition at some finite temperature, *i.e.* that the magnetization changes discontinuously from 0 to m_c at the transition. Later Yuval and Anderson [8, 34] used a scaling analysis to predict that the transition is critical. Their analysis predicted that the correlation length has an essential singularity at the transition,

$$\xi \sim \exp \left[\mathcal{O} \left(\frac{1}{\sqrt{T - T_c}} \right) \right]. \quad (79)$$

Only a decade and a half later the mixed order nature of the transition was proved rigorously by Aizenman *et al.* [9].

In addition to the structural similarity between Eqs. (1)-(2) and Eqs. (77)-(78), the IDSI model exhibits mixed order symmetry breaking transition point, which is qualitatively similar to the transition in the TIDSI model. However, the quantitative features of this transition, namely the jump of the magnetization from 0 to $m_c < 1$, and the essential singularity in the correlation length, as well as more subtle features, are different from the TIDSI, as discussed in [24, 25].

In terms of EVS, the authors are not aware of any systematic study of the extreme value theory of the IDSI model. However, it is known [9] that domains, as defined in the TIDSI, are microscopic in the IDSI model for any positive temperature. At the transition there is a macroscopic structure that emerges, but it is hidden and can be revealed in a Random Cluster Model perspective. Hence, it is plausible to guess that the extreme value statistics may follow a Gumbel distribution. Anyway the EVS, whatever form it has, will probably not show the features we discussed above for the TIDSI model.

B. Relation to the Poland-Scheraga Model

The Poland-Scheraga (PS) model [10] is a prototypical model for studying thermal denaturation of DNA molecules, which is the process in which the two strands of the DNA molecule separate upon heating. The PS model idealizes the DNA chain of size L as a set of alternating bound and denatured segments. The degrees of freedom are the lengths of these segments $\{l_1, l_2, \dots, l_N\}$. Bound segments contribute linearly to the energy, so that

$$\mathcal{H} = E_b \sum_{n=1}^{N/2} l_{2n-1}, \quad (80)$$

with the constraint $\sum_{n=1}^N l_n = L$. Here $E_b < 0$ is the binding energy, N is the total number of segments and we assumed that the first segment is bound. Denatured segments, also known as *loops*, carry no energy, but instead contribute to the entropy of a configuration, due to the flexibility of single stranded DNA. Treating the strands in a loop as random walkers which must meet implies that the entropy of a loop of size l takes the form

$$S = \tilde{\Delta} + sl - c \log l. \quad (81)$$

Here $\tilde{\Delta}$ and s are constants which depend on the geometry of the embedding space and the chemical properties of the DNA, and c — the loop exponent — is a universal parameter which depends only on dimensionality of the embedding space and topological properties of the DNA such as self avoidance. Therefore the Boltzmann weight of a specific configuration $\{l_1, l_2, \dots, l_N\}$ can be written as

$$e^{-\beta E_b l_1} \frac{e^{\tilde{\Delta} + s l_2}}{l_2^c} e^{-\beta E_b l_3} \frac{e^{\tilde{\Delta} + s l_4}}{l_4^c} \dots \quad (82)$$

This Boltzmann weight is equivalent to the one derived from an effective Hamiltonian

$$\mathcal{H}_{eff} = \sum_{n=1}^{N/2} E_b l_{2n-1} - \frac{1}{\beta} \sum_{n=1}^{N/2} (s l_{2n} - c \log l_{2n}). \quad (83)$$

Comparing Eq. (83) and Eq. (6) implies that the TIDSI can be presented as a variant of the PS model in which all segments are loops (and then the linear term can be gauged out). An important difference between the models is that in the PS model c is a universal parameter, while in the TIDSI C is a parameter in the Hamiltonian. Actually, as is discussed below, the role of c is played in the TIDSI by $\beta_c C$, where β_c is the inverse critical temperature. Other than this difference, the models are very similar, both in their definition and in their phenomenology. From the phenomenological perspective, the main difference is that in the TIDSI we consider the magnetization order parameter, for which the Hamiltonian is symmetric. The natural order parameter of the PS model is the fraction of loop base-pairs, which have no such symmetry. Because of this difference, in the PS model, the regime $1 < c < 2$ is considered to be a continuous transition, as the natural order parameters are continuous, while in the TIDSI the corresponding regime ($1 < \beta_c C < 2$) exhibits a mixed order transition. The reason is that the magnetization in the paramagnetic phase is protected by symmetry and hence cannot be different than 0, while no such symmetry protects the order parameters of the PS model (and the density of domains in the TIDSI model). Another difference between the phase diagrams, is that in the PS model, for $c < 1$ there is no transition (and there is also a condition on s and $\hat{\Delta}$). The TIDSI model, on the other hand, supports a transition for any value of its parameters, but the effective parameter $c = \beta_c C$ satisfies $c > 1$.

From the perspective of extreme value theory, the EVS of loops in the PS model should be very similar to the EVS of the TIDSI model. Bound segments, however, are microscopic for any $T < T_c$, and hence their EVS follow the Gumbel distribution.

V. CONCLUSION

To summarize, we have presented, in this paper, a thorough study of fluctuations of the size of the largest domain l_{\max} in the TIDSI model. We found that above the critical temperature $T > T_c$ for any $c > 1$, and for $c > 2$ also at criticality $T = T_c$, the asymptotic EVS is similar to that of i.i.d. variables, indicating that the correlations are effectively weak. However, for $c < 2$ at T_c as well as in the ferromagnetic phase $T < T_c$ for any $c > 1$, we have found novel extreme value distributions, which we have computed exactly (see Table I for a summary of the main results).

Studying the extreme value statistics of correlated variables is an active field of research, and a specifically intriguing avenue is the EVS of variables at criticality. In this work we focused on a novel aspect of this topic, namely the EVS at mixed order transitions. As discussed in section IV, it will be interesting to test the universality of the results found here, by studying EVS for different models exhibiting MOT phase transition. In particular, as mentioned above, the TIDSI model has many similarities to the Poland-Scheraga (PS) model for DNA denaturation, and it is easy to extend the results above for the EVS for the case of loop sizes in the PS model. It would be therefore interesting to study experimentally whether the actual loop sizes distribution resembles the EVS that was found in this paper. A related question is how real world details, such as base-pair heterogeneity [35] and topological constraints [36] affect the EVS of loops.

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Appendix A: A brief reminder on EVS for i.i.d. random variables

Given N i.i.d random variables $\{x_i\}_{i=1}^N$, the distribution of their maximum, $m = \max_i \{x_i\}$, properly shifted and scaled, converges in the large N limit to one of three max-stable distributions, depending on the tail of the parent PDF of x_i 's, $p(x)$:

1. If the support of $p(x)$ has an upper cutoff b , such that $p(x) \sim (b-x)^{\alpha-1}$ when $x \rightarrow b$, with $\alpha > 0$, then the limiting cumulative distribution of the maximum is given by the Weibull distribution:

$$P_1(z) = \Pr(m \leq z) \approx \begin{cases} \exp\left(-\left(\frac{b-z}{a_N}\right)^\alpha\right) & z < b \\ 1 & z \geq b \end{cases}, \quad N \rightarrow \infty, \quad (\text{A1})$$

where a_N depends on $p(x)$.

2. If the support of $p(x)$ is unbounded and if it has a power-law tail, $p(x \gg 1) \sim x^{-\alpha-1}$, then the limiting cumulative distribution of m is given by the Fréchet distribution:

$$P_1(z) \approx \begin{cases} 0 & z \leq 0 \\ \exp\left[-\left(\frac{z}{a_N}\right)^{-\alpha}\right] & z > 0 \end{cases}, \quad N \rightarrow \infty, \quad (\text{A2})$$

where a_N depends on $p(x)$.

3. If the support of $p(x)$ is unbounded and decays faster than any power-law for large x , then the limiting cumulative distribution of m is given by the Gumbel distribution

$$P_1(z) \approx \exp\left(-\exp\left(-\left(\frac{z-b_N}{a_N}\right)\right)\right), \quad N \rightarrow \infty. \quad (\text{A3})$$

Here again a_N and b_N depend on $p(x)$.

Appendix B: Analysis of the function $H_1(u)$

In this appendix, we study the function $H_1(u)$ and derive its explicit expression for $1 < u < 2$ given in Eq. (19). We recall that $H_1(u)$ is defined by the following relation [see Eq. (18)]:

$$\int_0^\infty e^{-wu} H_1(u) u^{c-2} du = \frac{\Gamma(c-1)}{w^{c-1}} \frac{\Gamma(1-c, w)}{\Gamma(1-c, w) - \Gamma(1-c)}, \quad (\text{B1})$$

where $\Gamma(\alpha, z) = \int_z^\infty x^{\alpha-1} e^{-x} dx$ is the incomplete gamma function. To analyze $H_1(u)$ it is convenient to expand the right hand side of Eq. (B1) and write the inverse Laplace transform as

$$\begin{aligned} H_1(u) u^{c-2} &= \int_{a-i\infty}^{a+i\infty} \frac{dw}{2\pi i} e^{wu} \frac{\Gamma(c-1)}{w^{c-1}} \frac{\Gamma(1-c, w)}{\Gamma(1-c, w) - \Gamma(1-c)} \\ &= -\sum_{n=1}^\infty \int_{a-i\infty}^{a+i\infty} \frac{dw}{2\pi i} e^{wu} \frac{\Gamma(c-1)}{w^{c-1}} \left[\frac{\Gamma(1-c, w)}{\Gamma(1-c)} \right]^n, \end{aligned} \quad (\text{B2})$$

where $a > 0$ such that the singularities of the integrand, namely the negative real axis which is a branch cut and $w = 0$ which is a branch point (for non-integer values c) or a pole (for integer values of c), are to the left of the Bromwich contour. Apart from that, the integrand has no other singularity. On the other hand, for large complex w it is easy to see that

$$\Gamma(1 - c, w) \sim \frac{e^{-w}}{w^c}, \quad |w| \rightarrow \infty. \quad (\text{B3})$$

Therefore, this implies that

$$\int_{a-i\infty}^{a+i\infty} \frac{dw}{2\pi i} e^{wu} \frac{\Gamma(c-1)}{w^{c-1}} \left[\frac{\Gamma(1-c, w)}{\Gamma(1-c)} \right]^n = 0, \text{ for } u < n, \quad (\text{B4})$$

since the integral over w can be computed by closing the Bromwich contour to the right. Therefore, from Eqs. (B2) and (B4) one obtains (i) that $H_1(u) = 0$ for $u < 1$ – which is expected since $l_{\max} \leq L$ and (ii) that, for $1 < u < 2$, $H_1(u)$ is determined only by the term $n = 1$ in Eq. (B2). This yields, for $1 < u < 2$:

$$\begin{aligned} H_1(u) u^{c-2} &= -\frac{\Gamma(c-1)}{\Gamma(1-c)} \int_{a-i\infty}^{a+i\infty} \frac{e^{wu}}{w^{c-1}} \int_w^\infty \frac{e^{-\eta}}{\eta^c} d\eta dw \\ &= -\frac{\Gamma(c-1)}{\Gamma(1-c)} \int_{a-i\infty}^{a+i\infty} \frac{e^{wu}}{w^{c-1}} \int_0^\infty \frac{e^{-(wz+w)}}{(wz+w)^c} w dz dw \\ &= -\frac{\Gamma(c-1)}{\Gamma(1-c)} \int_0^\infty \int_{a-i\infty}^{a+i\infty} \frac{e^{w(u-z-1)}}{w^{2c-2} (z+1)^c} dz dw \\ &= -\frac{\Gamma(c-1)}{\Gamma(1-c)} \int_0^\infty \frac{(u-z-1)^{2c-3}}{\Gamma(2c-2) (z+1)^c} \Theta(u-z-1) dz \\ &= -\frac{\Gamma(c-1)}{\Gamma(1-c)\Gamma(2c-1)} (u-1)^{2c-2} {}_2F_1(1, c, 2c-1, 1-u), \end{aligned} \quad (\text{B5})$$

which yields the result announced in Eq. (19). In particular, it behaves as $H_1(u) \sim u^{2c-1}$ when $u \rightarrow 1$ from above.

The expansion in Eq. (B2) shows that $H_1(u)$ has actually singularities at any integer values of u . One can indeed show, from Eq. (B2) that $H_1(k+\epsilon) - H_1(k-\epsilon) \sim \epsilon^{(k+1)c-2}$, with k an integer, as $\epsilon \rightarrow 0$.

Appendix C: Exact numerical evaluation of EVS for TIDSI

The simple structure of the TIDSI model allows us to calculate efficiently the distribution of its largest domain. The basic object is the truncated partition function $W_0(x|L)$ which is the sum of weights of TIDSI configurations of size L for which the maximal domain is smaller than x . The formula for $W_0(x|L)$ is given in Eq. (25), and it can be used to derive a recursion relation for $W_0(x|L)$. For any $x \geq 1$ one has indeed

$$W_0(x|L=0) = 1 \quad (\text{C1})$$

$$W_0(x|L=1) = e^{-\beta\Delta} \quad (\text{C2})$$

$$W_0(x|L) = \sum_{l=1}^{\min(x,L)} W_0(x|L-l) e^{-\beta\Delta} l^{-c}. \quad (\text{C3})$$

Using this together with Eq. (24), recalling that $Z(L) = \lim_{x \rightarrow \infty} W_0(x|L) = W_0(L|L)$ the distribution of the largest domain of the TIDSI model $P_1(x|L)$ can be numerically evaluated in a straightforward way.

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